

COVARIANT DERIVATIVES AND CONNECTIONS

COVARIANT DERIVATIVE $\nabla_\mu (j)$

COVARIANT BASIS INDEPENDENT

$\nabla_\mu \phi(x) \Rightarrow$ vector \checkmark
 $\nabla_\mu v^\nu$ IS A TENSOR \checkmark
 and so on

MOTIVATION

MATHS

DERIVATIVES $\partial_\mu \phi(x) \equiv \phi(x), \mu$

VECTOR \checkmark

$\partial_\mu v^\nu \equiv v^\nu, \mu$

NOT A TENSOR
 DOES NOT TRANSFORM AS TENSOR DOES
 Physical quantities do not depend on basis

PHYSICS

CONSERVED QUANTITIES or how they evolve

$\partial_\mu T^{\mu\nu} = 0$

FLAT SPACE

GENERALIZE

$(j)_\mu T^{\mu\nu} = 0$

CURVED SPACE

$\nabla_\mu = ?$

It looks like ∂_μ

in flat space (and inertial coords) Cartesian c.

and/or it transforms as a tensor (otherwise curved space)

Properties
 Linearity
 Leibniz rule ("chain rule")

velocity of an object should be the same if you use coordinates of polar coordinates!

$(j)^\alpha \equiv \Gamma^\alpha_\beta \gamma^\beta$

CHEISTOFFEL SYMBOLS NOT TENSORS
 DON'T FOLLOW THE TENSOR TRANSFORMATION RULES
 + Properties (torsion)

LEVI-CIVITA CONNECTION $\Gamma^\alpha_\beta \gamma$ ($g_{\mu\nu}$)

Γ^α_β MAY NOT depend on $g_{\mu\nu}$

BUT

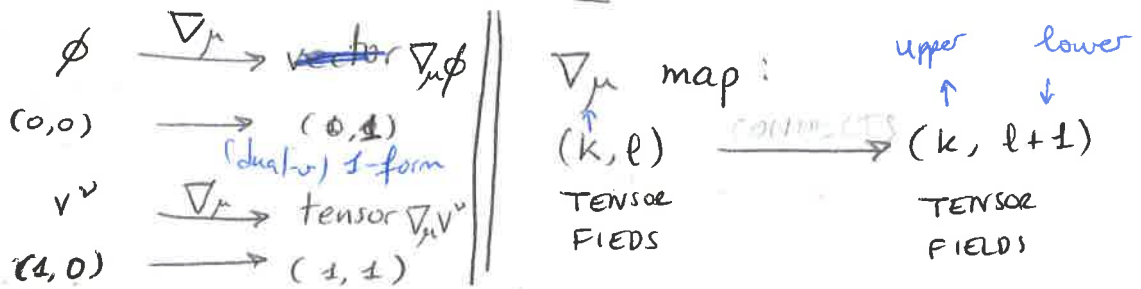
Given $g_{\mu\nu} \rightarrow \Gamma^\alpha_\beta$ unique
 $\nabla_\mu g_{\mu\nu} = 0$ metricity condition.

+ example.

MORE NEXT WEEK

① COVARIANT DERIVATIVE ∇_μ

1.1 HOW DOES ∇_μ LOOK LIKE?



Requirements: (In order to be a derivative)

(1) Linearity $\nabla(\alpha T + \beta S) = \alpha \nabla T + \beta \nabla S$, $\alpha, \beta \equiv \text{const}$

(2) Leibniz rule $\nabla(T \otimes S) = (\nabla T) \otimes S + T \otimes (\nabla S)$
 ↑ tensor product

Expression:

$\nabla_\mu = \partial_\mu + \text{something which guarantees covariance}$

$$V'^\lambda = \frac{\partial x'^\lambda}{\partial x^\nu} V^\nu$$

$$w_\mu = \frac{\partial x^\nu}{\partial x'^\mu} w_\nu$$

• Vector:

$$\nabla_\mu V^\nu = \partial_\mu V^\nu + \Gamma_{\mu\lambda}^\nu V^\lambda \quad (*) \equiv \partial_\mu V^\nu + \Gamma_{\mu\lambda}^\nu V^\lambda$$

Covariance:

$\{x^\mu\}$ basis \rightarrow $\{\tilde{x}^\mu\}$ basis $\Rightarrow \nabla_{\tilde{\mu}} V'^{\lambda} = \frac{\partial x^\mu}{\partial \tilde{x}^{\tilde{\mu}}} \frac{\partial \tilde{x}^\lambda}{\partial x^\nu} \nabla_\mu V^\nu$ [A]
 (Recall how x_μ and x^μ transforms)

$$\nabla_{\tilde{\mu}} V'^{\lambda} \stackrel{(*)}{=} \underbrace{\partial_{\tilde{\mu}} V'^{\lambda}}_{\text{change of coord's}} + \Gamma_{\tilde{\mu}\tilde{\alpha}\tilde{\beta}}^{\lambda} V'^{\tilde{\beta}} \stackrel{(*)}{=} \frac{\partial x^\mu}{\partial \tilde{x}^{\tilde{\mu}}} \frac{\partial \tilde{x}^\lambda}{\partial x^\nu} \partial_{\tilde{\mu}} V^\nu + \frac{\partial x^\mu}{\partial \tilde{x}^{\tilde{\mu}}} V^\nu \frac{\partial}{\partial \tilde{x}^{\tilde{\mu}}} \frac{\partial \tilde{x}^\lambda}{\partial x^\nu} + \Gamma_{\tilde{\mu}\tilde{\alpha}\tilde{\beta}}^{\lambda} \frac{\partial x^{\tilde{\alpha}}}{\partial x^\nu} V^{\tilde{\beta}} \quad [B]$$

Covariance argument $\Rightarrow [A] \equiv [B]$

$$\Gamma_{\tilde{\mu}\tilde{\alpha}\tilde{\beta}}^{\lambda} = \frac{\partial x^\mu}{\partial \tilde{x}^{\tilde{\mu}}} \frac{\partial x^\lambda}{\partial \tilde{x}^{\tilde{\alpha}}} \frac{\partial \tilde{x}^\lambda}{\partial x^\nu} \Gamma_{\mu\alpha}^\nu - \frac{\partial x^\mu}{\partial \tilde{x}^{\tilde{\mu}}} \frac{\partial x^\lambda}{\partial \tilde{x}^{\tilde{\alpha}}} \frac{\partial \tilde{x}^\lambda}{\partial x^\nu} \frac{\partial \tilde{x}^\nu}{\partial x^\alpha}$$

free indices No tensor

1.2 Then:

* SCALARS

$$\nabla_\mu \phi(x) = \partial_\mu \phi(x)$$

* VECTORS

$$\nabla_\mu V^\nu = \partial_\mu V^\nu + \Gamma_{\mu\lambda}^\nu V^\lambda$$

$V_\alpha = \Gamma_{\alpha\mu}^\nu V^\mu$

* 1-Forms

$$\nabla_\mu \omega_\nu = \partial_\mu \omega_\nu - \Gamma_{\mu\nu}^\lambda \omega_\lambda$$

(eq 3.17) Page 97

* General tensor (look it up Carroll, Wald)

$$\nabla_\rho g_{\mu\nu} = 0 \quad \text{Metricity condition}$$

1.3. Property:

∇_μ commutes with contractions:

$$T^\mu_{\nu\rho} \rightarrow \nabla_\mu (T^\lambda_{\nu\rho}) \equiv 1^{st} \nabla_\mu T^\lambda_{\nu\rho} + 2^{nd} \text{ contraction } \lambda, \nu$$

Divergence:

$$\nabla_\mu V^\mu = \frac{1}{\sqrt{|g|}} \partial_\mu (\sqrt{|g|} V^\mu)$$

Not only raising or lowering indices since $\Gamma_{\mu\nu}^\lambda$ is a symbol.

ASSOCIATED TO A METRIC

② CONNECTION

$$\Gamma_{\alpha\beta}^\sigma < \nabla_\mu$$

$$g_{\mu\nu} \Rightarrow \Gamma_{\alpha\beta}^\sigma \text{ unique} \Rightarrow \nabla_\mu \text{ unique Levi-Civita c.}$$

Name connection comes from the fact it is used to "transport" vectors from the tangent space to the dual.

(1) Metricity condition

+ symmetric permutations
of $g^{\sigma\rho}$

$$- \nabla_\rho g_{\mu\nu} = \partial_\rho g_{\mu\nu} - \Gamma_{\rho\mu}^\lambda g_{\lambda\nu} - \Gamma_{\rho\nu}^\lambda g_{\mu\lambda} = 0$$

$$+ \nabla_\mu g_{\nu\rho} = \dots$$

$$+ \nabla_\nu g_{\rho\mu} = \dots$$



$$\Gamma_{\mu\nu}^\sigma = \frac{1}{2} g^{\sigma\rho} [\partial_\mu g_{\rho\nu} + \partial_\nu g_{\rho\mu} - \partial_\rho g_{\mu\nu}]$$

(2) Property: Torsion free \Rightarrow

$$\Gamma_{\mu\nu}^\sigma = \Gamma_{\nu\mu}^\sigma$$

$$T^\lambda_{\mu\nu} = \Gamma_{\mu\nu}^\lambda - \Gamma_{\nu\mu}^\lambda = 2 \Gamma_{[\mu\nu]}^\lambda \text{ antisymmetric in lower indices} \Rightarrow \text{Torsion free.}$$

∇_μ symmetric in lower index

$$\nabla_\mu \nabla_\nu f = \nabla_\nu \nabla_\mu f$$

At the end.

EXAMPLE

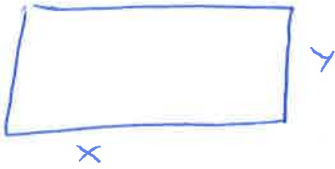
$$\Gamma_{\mu\nu}^{\sigma} = \frac{1}{2} g^{\sigma\lambda} [\partial_{\mu} g_{\lambda\nu} + \partial_{\nu} g_{\lambda\mu} - \partial_{\lambda} g_{\mu\nu}]$$

2D Flat space

* CARTESIAN COORDINATES

$$ds^2 = dx^2 + dy^2$$

$$g_{ij} = \begin{bmatrix} 1 & \\ & 1 \end{bmatrix}; g^{ij} = \begin{bmatrix} 1 & \\ & 1 \end{bmatrix}$$



NO NEED FOR CALCULATIONS

$$\Gamma_{ij}^k = 0$$

∇_{μ} is constructed such that ∂_{μ} is recovered in flat space and inertial coord's.

CHANGE OF COORD'S

* POLAR COORDINATES

$$ds^2 = dr^2 + r^2 d\theta^2$$

$$g_{ij} = \begin{bmatrix} 1 & \\ & r^2 \end{bmatrix}; g^{ij} = \begin{bmatrix} 1 & \\ & 1/r^2 \end{bmatrix}$$



$i, j, k = \{r, \theta\}$

- $k=r$
- $\hookrightarrow j=r$
- $\hookrightarrow j=\theta$
- $\hookrightarrow i=\theta$
- $\hookrightarrow j=r$
- $\hookrightarrow j=\theta$
- $k=\theta$ (same)

$$\Gamma_{rr}^r = 0$$

$$\Gamma_{r\theta}^r \stackrel{sym}{=} \Gamma_{\theta r}^r = 0$$

$$\Gamma_{\theta\theta}^r = \frac{1}{2} g^{r\lambda} (\partial_{\theta} g_{\lambda\theta} + \partial_{\theta} g_{\theta\lambda} - \partial_{\lambda} g_{\theta\theta})$$

$$\Gamma_{rr}^{\theta} = 0$$

$$= \frac{1}{2} g^{\theta\lambda} (\partial_r g_{\lambda r} + \partial_r g_{r\lambda} - \partial_{\lambda} g_{rr})$$

$$\Gamma_{r\theta}^{\theta} = \Gamma_{\theta r}^{\theta} = 1/r$$

$$\Gamma_{\theta\theta}^{\theta} = 0$$

$$= \frac{1}{2} g^{\theta\lambda} (-\partial_r g_{\lambda\theta}) = -r$$

ρ sum over r & θ

Torsion-free demonstration?